

Edifice Energy Proficient Wireless Sensor Networks

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Abstract - Hand Gesture awareness systems have been considered as the able-bodied and well-made structures with the purpose of deciphering gestures, making use of appropriate algorithms to accomplish the focus task. So far, number strategies have been used to perceive the gestures; many have their own benefits but additionally have few shortcomings like responsiveness, classification, accuracy etc. Hence, gives the want to use such algorithms every of which is unique in its own tremendous and creative way and strive to deliver out the excellent viable results. Our proposed work focuses on extracting the elements using Scale-Invariant Feature Transform (SIFT) algorithm, optimizing those aspects the usage of Genetic Algorithm and subsequently classifying the gestures the usage of Back Propagation Neural Networks (BPNN). By doing this our system obtains higher overall performance in terms of classification and faster response time or delayed outputs.

Keywords - Genetic Algorithm; BPNN; Performance, Gesture interpretation; SIFT Algorithm.

I. INTRODUCTION TO HAND GESTURES

Hand gesture awareness plays a super role in spotting the gestures and acts as a bridge between humans and computers so that computer systems can come to know human physique languages and provide an efficient intercommunication in a steady manner. The image is in reality a feature of $f(x, y)$ and takes its magnitude at a location (x, y) . Researchers have many methods to screen the captured gestures. Every gesture attention gadget has three foremost building parts primarily based on which it includes the focus process.

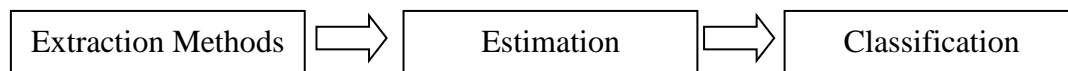


Fig.1: Gesture recognition steps

The very first step in the attention section is known as segmentation. Segmentation partitions the captured photo into discrete components by means of bounds. The best and really useful way used for segmentation of hand is the skin color, for it is changeless to size, translation, and rotation facets of the hand[1]. Once the image is segmented, the next step is extracting the unique houses or elements from the segmented image. Finally, gesture classification approach is used to interpret the reconstructed gesture with acceptable classification algorithm. Misclassification of gestures degrades the picture quality and leads to bad overall performance of the system. These structures serve a vast vary of purposes on a number of domains together with scientific systems, virtual environments, smart examination, signal language translation etc.

A. Problems encountered in Hand gesture cognizance

During the learn about of many approaches, it has been discovered that gesture verification issues many troubles and need similarly enhancements in order to get environment friendly

pattern matching. The issues encountered are as: Variation of illumination conditions: It capacity any trade in the lighting conditions has a horrific have an impact on on the extracted pores and skin region. Rotation Problem: It is the problem faced when the hand posture is moved in any order in the scene. Background Problem: A intricate history also creates issues when there are other objects round with the hand objects and might also have comparable skin color[8]. Scale Problem: This problem takes place if the hand poses have various sizes[2].Rotation problem: this concern arrives when hand is moved in any order in the backdrop. Translation Problem: The changing hand positions in differing pictures additionally leads to false depiction of the features. Difficulties in handling the training input and testing output: Artificial Neural Network (ANN) creates one network on only one layer which reasons lengthen in response time which is the hassle of foremost concern. Earlier work in the subject of hand gesture awareness for characteristic extraction was performed the use of Principal Component Analysis (PCA). PCA is a mathematical algorithm and has the trait to determine the Eigen values and Eigen vectors directly in the shape of a matrix. However, due to its massive matrices formation it turns into tedious to calculate the Eigen values and Eigen vectors and is noticeably sensitive to scaling. Also intelligent strategies like Artificial Neural Networks was once used as a mechanism for gesture classification and matching but lead to delayed response time and hampered device performance. Since, hand gesture systems are used for security purpose, it is fundamental that the gadget becomes efficient [3, 4].

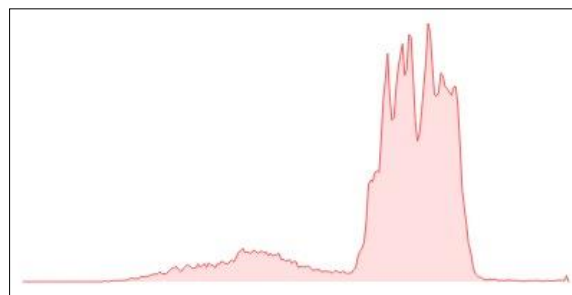
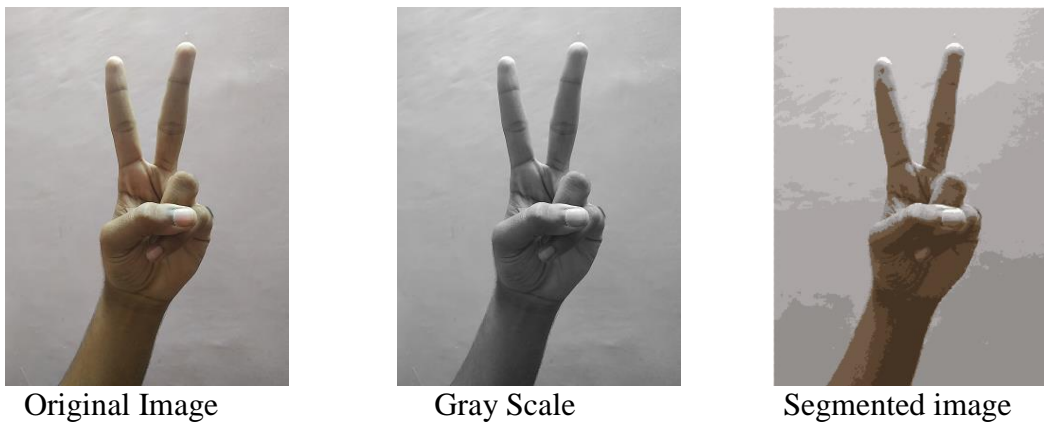
B. Proposed answer

Our proposed work takes three strategies into consideration. Our purpose is to overcome the above barriers and based totally on it we have used the embedded algorithms namely; Scale Invariant Feature Transform (SIFT), Genetic Algorithm for optimization and Back Propagation Neural Network.

II. TECHNIQUES USED

A. Scale Invariant Feature Transform

SIFT, is an algorithm to discover and spotlight neighborhood facets in pictures [5].By local elements we mean that for any object, special properties additionally called as the key factors are separated from its segmented image. The essential function of SIFT is to take a look at whether the photo is segmented suitable or not and then to calculate the wide variety of key features from the scalable picture and localize them. SIFT works by dividing the enter segmented scalable picture facts into modules and partitions it. For each step SIFT does a deep study to decide number of unique elements no longer solely in the centre of the photograph however additionally depicts them at the co-ordinates. SIFT is consistent to scaling, rotation, orientation troubles and has no have an impact on of noise factors. SIFT determines big amount of features even from a clutter of images, which lessens the prevalence of mistakes of different characteristic akin to errors. This detection, extracted from an education picture can later be used to point out the object in check images with rest of the objects.



Histogram of the Image

Fig2: segmentation process of hand

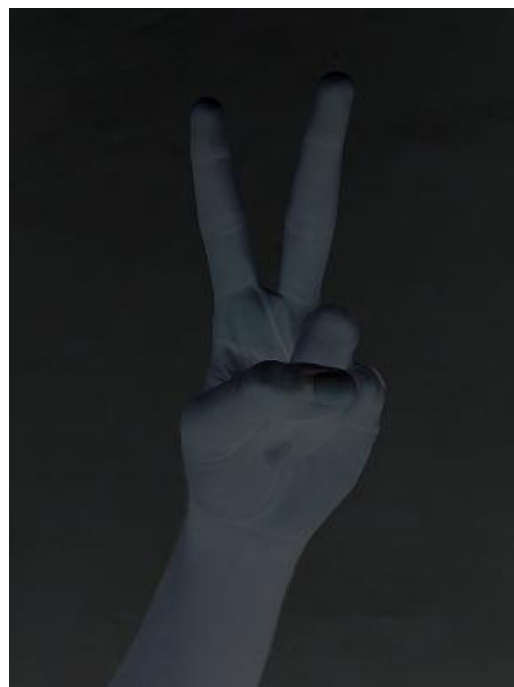


Fig3: key features of segmented image

B. Genetic Algorithm

A genetic algorithm is an analytical and investigative optimization technique, used when the search space is massive or too complex for analytical examination. It performs a detailed find out about of extracted facets in order to yield higher outcomes in an environment friendly manner. The persons in the populace are computed by way of fitness feature and match values. The operators namely; Selection, Crossover, Mutation raise the last task. Selection feature selects or initializes the chromosomes in a populace that are made to repeat every time producing better chromosomes than before. Crossover is used to fluctuate or interchange the subparts amongst chromosomes from one era to another. The mutation changes the gene values from its unique state. A random variable is created in a gene pool which let's know whether the unique bit is elevated or not. A genetic algorithm is a vigorous search approach requiring much less statistics to search efficiently to produce optimized output in an enormous search space and is free of derivatives[6][7].

117.02857142857142	362.0571428571429
158.62857142857143	235.88571428571427
118.4	78.62857142857143
189.71428571428572	60.34285714285714
194.28571428571428	181.4857142857143
215.77142857142857	232.22857142857143
177.82857142857142	305.8285714285714
105.14285714285714	292.1142857142857
59.885714285714286	395.8857142857143
84.11428571428571	352.9142857142857
144	393.6
158.17142857142858	345.6
106.97142857142858	236.34285714285716
120.68571428571428	186.05714285714285
117.48571428571428	141.71428571428572
108.8	100.57142857142857
132.57142857142858	106.51428571428572
143.54285714285714	154.5142857142857
155.42857142857142	171.88571428571427
162.74285714285713	146.28571428571428
165.02857142857144	117.94285714285714
169.6	92.34285714285714
192.9142857142857	41.142857142857146
194.28571428571428	82.28571428571429
189.71428571428572	128.45714285714286
182.4	171.42857142857142
196.11428571428573	176
202.5142857142857	193.37142857142857

Data Sets of the Genetic Algorithm

Equation :

Axes Type: XY

Pixel to Data

1. $x_data = (0.006241742345253541)*x_pixel + (-0.00046138402273143356)*y_pixel + (-0.2340358640889518)$
2. $y_data = (-0.0031165184931670397)*x_pixel + (-0.0028205362899053656)*y_pixel + (1.5372290892304266)$

Data to Pixel

1. $x_pixel = (148.11428571428567)*x_data + (-24.22857142857144)*y_data + (71.90891963155795)$
2. $y_pixel = (-163.65714285714282)*x_data + (-327.7714285714285)*y_data + (465.5581337757124)$

Angle

Theta0, 13.292055216321122

Theta1, 0.3279460360143623

Theta2, 356.94331300401393

Theta3, 74.07346051600788

C. Back Propagation Neural Network

Back Propagation Neural Network is comparable in structure with Artificial Neural Networks, on the other hand differ in processing. BPNN works faster and fastens the response time by using sending optimized information in a couple of layers in contrast to neural community which sends data in only a single layer. The error is traced returned to previous node. As a result, the delay in enter education and trying out output can be decreased to a large extent using BPNN which is a feed forward algorithm [9].

III. METHODOLOGY

A. SIFT ALGORITHM

Step1: The SIFT takes the got key features in its scenario. The image is looped with Gaussian filters at varying scales, accompanied by means of the difference of consecutive Gaussian-blurred image. This is known as as the Scale-space extrema detection. The key points generated are nothing however the most and minimal of the Gaussian variations represented as (DoG) proven as

$$D(x,y,\sigma)=L(x,y,ki\sigma) - L(x,y,kj\sigma), (1)$$

where $L(x,y,k\sigma)$ is the looping of actual image $I(x,y)$ with the blurred Gaussian image $G(x,y,k\sigma)$ at some scale $k\sigma$, and '*' is the looping factor such that

$$L(x,y,k\sigma) = G(x,y,k\sigma) * I(x,y) \quad (2)$$

Therefore, DoG, is the difference of Gaussian blur images at $k\sigma$ and $kj\sigma$. The procedure is performed using various octaves.

Step2: SIFT distills the key points situated on the edges and eliminates the less distinctive key features. This is called as key point localization[10]. The area of extremism, z , is given by:

$$Z = - [(d^2 D^{(-1)}) / [dx]^2]^{\wedge} dD/dx \quad (3)$$

Step3: This is the solution to get enduring rotation by providing some orientations based on the computations of Gradient Magnitude and direction belonging to that part. This step is called direction assigning. For an image sample $L(x, y)$ at ' σ ', the gradient magnitude, $m(x, y)$, and rotation, $\theta(x, y)$ are already evaluated as under

$$m(x,y) =$$

$$\sqrt{L(x+1,y) - L(x-1,y))^2 + (L(x,y+1) - L(x,y-1))^2}$$

$$\theta(x,y) = \arctan2(L(x,y+1) - L(x,y-1), L(x+1,y) - L(x-1,y))$$

Step4: This step is carried out for pixels to get matched and individual among neighboring features. Key feature descriptors commonly make an adaptation for 16 histograms, equipped in a 4x4 settlement, representing eight introduction containers, for the mindset compass bearings and the mid-purposes headings. Fig four explains the sift algorithm steps and Fig.5 suggests the genetic algorithm steps.

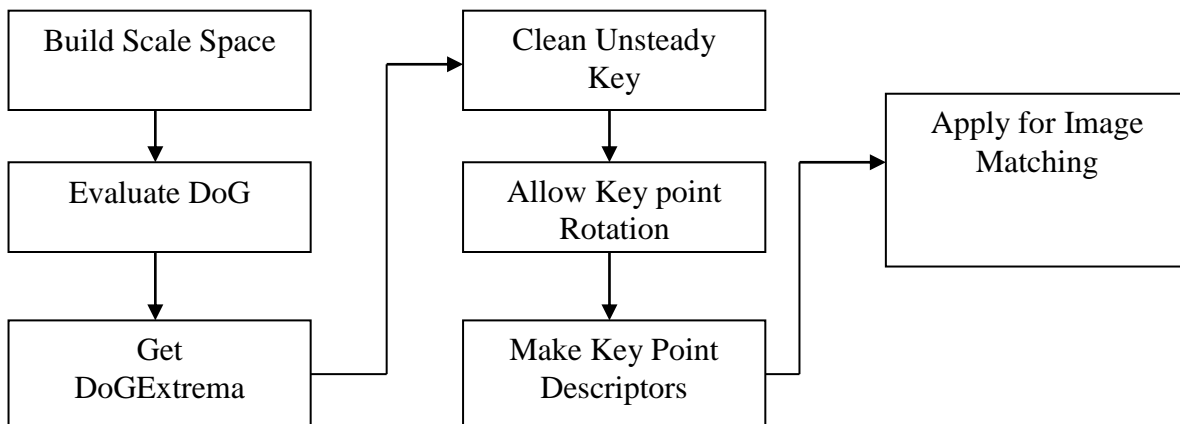


Fig4: Sift algorithm steps

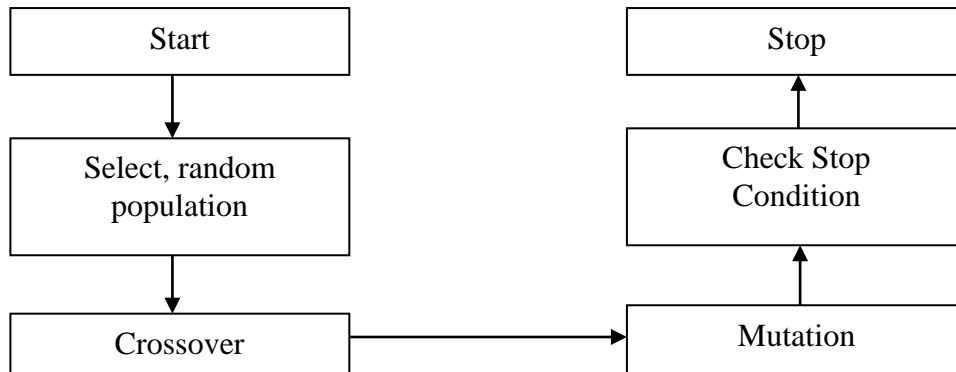


Fig.5: Genetic algorithm Step

IV. ALGORITHM FOR OVERALL WORKFLOW

- Step1: Upload photos of many categories
- Step2: pre-process and section these images
- Step3: Represent the segmented images graphically the usage of the histogram
- Step4: Use SIFT to boost key features
- Step5: Apply the Genetic algorithm to the above features
- Step6: Select population size and allow for crossover and mutation
- Step7: Using fitness function generate match values
- Step8: Classify Using Back propagation Neural Network
- Step9: Compute performance of the system

V. CONCLUSION AND FUTURE SCOPE

In this paper, we have taken three strategies into consideration viz SIFT algorithm, Genetic algorithm, and Back Propagation Neural Network by means of replacing the already present techniques. The device was planned with the high focal point on characteristic separation and optimization so as to reap correct gestures. However, in near future Back Propagation neural network can be introduced as a gesture identifier or interpreter to work on the grounds of expanded performance.

VI. REFERENCES

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